RoboEarth: Knowledge-exchange between robots

List of Publications

[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework, 

[C1] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
Learning Probability Distributions over Partially-Ordered Human Everyday Activities, 

[C1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
The RoboEarth language: Representing and Exchanging Knowledge about Actions, Objects, and Environments, 

[C2] Moritz Tenorth and Michael Beetz, 
Knowledge Processing for Autonomous Robot Control, 
AAAI Spring Symposium on Designing Intelligent Robots: Reintegrating AI, Stanford, CA, USA, March 26–28 2012.

[C3] Michael Beetz, Moritz Tenorth, Dejan Panceric and Benjamin Pitzer, 
Semantic Object Maps for Household Tasks, 

[C4] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine, 

[C5] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi, 
RoboEarth Action Recipe Execution, 

[C6] Moritz Tenorth and Michael Beetz, 
Exchange of Action-related Information among Autonomous Robots, 

[C7] Moritz Tenorth and Michael Beetz, 
A Unified Representation for Reasoning about Robot Actions, Processes, and their Effects on Objects, 

[C8] Moritz Tenorth, Koji Kamei, Satoru Satake, Takahiroy Miyashita and Norihiro Hagita, 
Towards a Networked Robot Architecture for Distributed Task Execution and Knowledge Exchange, 
Third International Workshop on Standards and Common Platforms for Robotics (SCPR 2012), in conjunction with SIMPAR 2012, Tsukuba, Japan, November 5 2012.
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