Naive Physics reasoning by simulation  

List of Publications

[C1] Lars Kunze, Mihai Emanuel Dolha, Emitza Guzman and Michael Beetz, 
Simulation-based Temporal Projection of Everyday Robot Object Manipulation, 
Yolum, Tumer, Stone and Sonenberg(Eds.), Proc. of the 10th Int. Conf. on Autonomous 
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[C2] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz, 
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Robot Object Manipulation, 
2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), San 

[C1] Lorenz Mösenlechner and Michael Beetz, 
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