Naive Physics reasoning by simulation

List of Publications

[C1] Lars Kunze, Mihai Emanuel Dolha, Emitza Guzman and Michael Beetz,
*Simulation-based Temporal Projection of Everyday Robot Object Manipulation*,
Yolum, Tumer, Stone and Sonenberg(Eds.), *Proc. of the 10th Int. Conf. on Autonomous Agents and Multiagent Systems (AAMAS 2011)*, Taipei, Taiwan, IFAAMAS, May, 2–6 2011.

[C2] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz,
*Logic Programming with Simulation-based Temporal Projection for Everyday Robot Object Manipulation*,

[C1] Lorenz Möslenlechner and Michael Beetz,
*Using Physics- and Sensor-based Simulation for High-fidelity Temporal Projection of Realistic Robot Behavior*,
*19th International Conference on Automated Planning and Scheduling (ICAPS’09)*, 2009.