KnowRob: Knowledge processing for robots List of Publications


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List of Publications

[C5] Moritz Tenorth and Michael Beetz,
Knowledge Processing for Autonomous Robot Control,
AAAI Spring Symposium on Designing Intelligent Robots: Reintegrating AI, Stanford, CA, USA, March 26–28 2012.

[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer,
Semantic Object Maps for Household Tasks,

[C7] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr,
CRAM – a Cognitive Robot Abstract Machine,

[C8] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi,
RoboEarth Action Recipe Execution,

[C9] Moritz Tenorth and Michael Beetz,
Exchange of Action-related Information among Autonomous Robots,

[C10] Moritz Tenorth and Michael Beetz,
A Unified Representation for Reasoning about Robot Actions, Processes, and their Effects on Objects,

[C11] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz,
Semantic Object Maps for Robotic Housework - Representation, Acquisition and Use,

The SHERPA project: smart collaboration between humans and ground-aerial robots for improving rescuing activities in alpine environments,
IEEE International Symposium on Safety, Security, and Rescue Robotics (SSRR), College Station, Texas, USA, Nov. 5-8 2012.

[C13] Moritz Tenorth, Koji Kamei, Satoru Satake, Takahiro Miyashita and Norihiro Hagita,
Towards a Networked Robot Architecture for Distributed Task Execution and Knowledge Exchange,
Third International Workshop on Standards and Common Platforms for Robotics (SCPR 2012), in conjunction with SIMPAR 2012, Tsukuba, Japan, November 5 2012.

[J1] Moritz Tenorth, Ulrich Klank, Dejan Pangercic and Michael Beetz,
Web-enabled Robots – Robots that Use the Web as an Information Resource,


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[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch,
Towards Automated Models of Activities of Daily Life,

[J2] Michael Beetz, Dominik Jain, Lorenz Mösenlechner and Moritz Tenorth,
Towards Performing Everyday Manipulation Activities,

[J3] Moritz Tenorth, Dominik Jain and Michael Beetz,
Knowledge Representation for Cognitive Robots,

[C1] Moritz Tenorth, Daniel Nyga and Michael Beetz,
Understanding and Executing Instructions for Everyday Manipulation Tasks from the World Wide Web,

[C2] Moritz Tenorth and Michael Beetz,
Priming Transformational Planning with Observations of Human Activities,

[C3] Dejan Pangercic, Moritz Tenorth, Dominik Jain and Michael Beetz,
Combining Perception and Knowledge Processing for Everyday Manipulation,

[C4] Michael Beetz, Lorenz Mösenlechner and Moritz Tenorth,
CRAM – A Cognitive Robot Abstract Machine for Everyday Manipulation in Human Environments,

[C5] Lars Kunze, Moritz Tenorth and Michael Beetz,
Putting People’s Common Sense into Knowledge Bases of Household Robots,
33rd Annual German Conference on Artificial Intelligence (KI 2010), Karlsruhe, Germany, Springer, 151-159, September 21-24 2010.

[C6] Moritz Tenorth, Lars Kunze, Dominik Jain and Michael Beetz,
KNOWROB-MAP – Knowledge-Linked Semantic Object Maps,

[R1] Moritz Tenorth and Michael Beetz,
Deliverable D5.2: The RoboEarth Language – Language Specification,
[C1] Dejan Pangercic, Rok Tavcar, Moritz Tenorth and Michael Beetz,
Visual Scene Detection and Interpretation using Encyclopedic Knowledge and
Formal Description Logic,
Proceedings of the International Conference on Advanced Robotics (ICAR), Munich, Germany, June 22 - 26 2009.

[C2] Moritz Tenorth and Michael Beetz,
KnowRob – Knowledge Processing for Autonomous Personal Robots,

[C3] Moritz Tenorth, Jan Bandouch and Michael Beetz,
The TUM Kitchen Data Set of Everyday Manipulation Activities for Motion
Tracking and Action Recognition,
IEEE International Workshop on Tracking Humans for the Evaluation of their Motion in

[C4] Michael Beetz, Jan Bandouch, Dominik Jain and Moritz Tenorth,
Towards Automated Models of Activities of Daily Life,
First International Symposium on Quality of Life Technology – Intelligent Systems for

[R1] Moritz Tenorth, Daniel Nyga and Michael Beetz,
Understanding and Executing Instructions for Everyday Manipulation Tasks from the World Wide Web,
IAS group, Technische Universität München, Fakultät für Informatik, 2009.

[C1] Michael Beetz, Freek Stulp, Bernd Radig, Jan Bandouch, Nico Blodow, Mihai Dolha, Andreas Fedrizzi, Dominik Jain, Uli Klank, Ingo Kresse, Alexis Maldonado, Zoltan Marton, Lorenz Mösenlechner, Federico Ruiz, Radu Bogdan Rusu and Moritz Tenorth,
The Assistive Kitchen – A Demonstration Scenario for Cognitive Technical Systems,
IEEE 17th International Symposium on Robot and Human Interactive Communication (RO-MAN), Muenchen, Germany, 1-8, 2008.

[C2] Moritz Tenorth and Michael Beetz,
Towards Practical and Grounded Knowledge Representation Systems for Autonomous Household Robots,