RoboSherlock: Unstructured Information Processing Framework for Robotic Perception,
Busoniu, Lucian, Tamás and Levente(Eds.), Handling Uncertainty and Networked Structure in Robot Control, 181-208, 2015.

[C1] Michael Beetz, Ferenc Bálint-Benczédi, Nico Blodow, Daniel Nyga, Thiemo Wiedemeyer and Zoltán-Csaba Marton,
RoboSherlock: Unstructured Information Processing for Robot Perception,

[C1] Daniel Nyga and Michael Beetz,
Everything Robots Always Wanted to Know about Housework (But were afraid to ask),

[C1] Daniel Nyga, Moritz Tenorth and Michael Beetz,
How-Models of Human Reaching Movements in the Context of Everyday Manipulation Activities,

[C1] Moritz Tenorth, Daniel Nyga and Michael Beetz,
Understanding and Executing Instructions for Everyday Manipulation Tasks from the World Wide Web,

[R1] Moritz Tenorth, Daniel Nyga and Michael Beetz,
Understanding and Executing Instructions for Everyday Manipulation Tasks from the World Wide Web,
IAS group, Technische Universität München, Fakultät für Informatik, 2009.