Ulrich Klank

List of Publications

[C1] Ulrich Klank, Lorenz Mösenlechner, Alexis Maldonado and Michael Beetz,
Robots that Validate Learned Perceptual Models,
IEEE International Conference on Robotics and Automation (ICRA), St. Paul, MN, USA,
May 14–18 2012.

[PhD1] Ulrich Klank,
Everyday Perception for Mobile Manipulation in Human Environments,
Technische Universität München, 2012.

[J1] Moritz Tenorth, Ulrich Klank, Dejan Pangercic and Michael Beetz,
Web-enabled Robots – Robots that Use the Web as an Information Resource,

[C1] Ulrich Klank, Daniel Carton and Michael Beetz,
Transparent Object Detection and Reconstruction on a Mobile Platform,
IEEE International Conference on Robotics and Automation (ICRA), Shanghai, China,
May, 9–13 2011.

[C2] Michael Beetz, Ulrich Klank, Alexis Maldonado, Dejan Pangercic and Thomas Rühr,
Robotic Roommates Making Pancakes - Look Into Perception-Manipulation Loop,
IEEE International Conference on Robotics and Automation (ICRA), Workshop on Mobile

[C3] Michael Beetz, Ulrich Klank, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan
Pangercic, Thomas Rühr and Moritz Tenorth,
Robotic Roommates Making Pancakes,
11th IEEE-RAS International Conference on Humanoid Robots, Bled, Slovenia, October,
26–28 2011.

[C4] Ingo Kresse, Ulrich Klank and Michael Beetz,
Multimodal Autonomous Tool Analyses and Appropriate Application,
11th IEEE-RAS International Conference on Humanoid Robots, Bled, Slovenia, October,
26–28 2011.

[J1] Michael Beetz, Freek Stulp, Piotr Esden-Tempski, Andreas Fedrizzi, Ulrich Klank, Ingo
Kresse, Alexis Maldonado and Federico Ruiz,
Generality and Legibility in Mobile Manipulation,

[C1] Alexis Maldonado, Ulrich Klank and Michael Beetz,
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ger torque information,
2010 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), Tai-
peh, Taiwan, 2586-2591, October 18-22 2010.
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