Naive Physics reasoning by simulation

List of Publications

[C1] Lars Kunze, Mihai Emanuel Dolha, Emitza Guzman and Michael Beetz,
Simulation-based Temporal Projection of Everyday Robot Object Manipulation,
Yolum, Tumer, Stone and Sonenberg (Eds.), Proc. of the 10th Int. Conf. on Autonomous
Agents and Multiagent Systems (AAMAS 2011), Taipei, Taiwan, IFAAMAS, May, 2–6
2011.

[C2] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz,
Logic Programming with Simulation-based Temporal Projection for Everyday
Robot Object Manipulation,
2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), San

[C1] Lorenz Mösenlechner and Michael Beetz,
Using Physics- and Sensor-based Simulation for High-fidelity Temporal Pro-
cection of Realistic Robot Behavior,
19th International Conference on Automated Planning and Scheduling (ICAPS’09), 2009.