Naive Physics reasoning by simulation

List of Publications

[C1] Lars Kunze, Mihai Emanuel Dolha, Emitza Guzman and Michael Beetz, 
Simulation-based Temporal Projection of Everyday Robot Object Manipula- 
tion, 
Yolum, Tumer, Stone and Sonenberg(Eds.), Proc. of the 10th Int. Conf. on Autonomous 
Agents and Multiagent Systems (AAMAS 2011), Taipei, Taiwan, IFAAMAS, May, 2–6 
2011.

[C2] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz, 
Logic Programming with Simulation-based Temporal Projection for Everyday 
Robot Object Manipulation, 
2011 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), San 

[C1] Lorenz Mösenlechner and Michael Beetz, 
Using Physics- and Sensor-based Simulation for High-fidelity Temporal Pro- 
jection of Realistic Robot Behavior, 
19th International Conference on Automated Planning and Scheduling (ICAPS’09)., 2009.