Cogito: Plan-based Control of Robotic Agents

[List of Publications]

[C1] Ulrich Klank, Lorenz Mösenlechner, Alexis Maldonado and Michael Beetz, 
Robots that Validate Learned Perceptual Models, 
IEEE International Conference on Robotics and Automation (ICRA), St. Paul, MN, USA, 
May 14–18 2012.

[C2] Ingo Kresse and Michael Beetz, 
Movement-aware Action Control – Integrating Symbolic and Control-theoretic 
Action Execution, 
IEEE International Conference on Robotics and Automation (ICRA), St. Paul, MN, USA, 
May 14–18 2012.

[C3] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine, 

[C1] Lorenz Mösenlechner and Michael Beetz, 
Parameterizing Actions to have the Appropriate Effects, 

[C2] Michael Beetz, Ulrich Klank, Ingo Kresse, Alexis Maldonado, Lorenz Mösenlechner, Dejan Pangercic, Thomas Rühr and Moritz Tenorth, 
Robotic Roommates Making Pancakes, 
11th IEEE-RAS International Conference on Humanoid Robots, Bled, Slovenia, October, 
26–28 2011.

[J1] Michael Beetz, Dominik Jain, Lorenz Mösenlechner and Moritz Tenorth, 
Towards Performing Everyday Manipulation Activities, 

[J2] Michael Beetz, Martin Buss and Bernd Radig, 
Learning from Humans – Cognition-enabled Computational Models of Everyday Activity, 
Künstliche Intelligenz, 2010.

[C1] Michael Beetz, Lorenz Mösenlechner and Moritz Tenorth, 
CRAM – A Cognitive Robot Abstract Machine for Everyday Manipulation in Human Environments, 
IEEE/RSJ International Conference on Intelligent Robots and Systems, Taipei, Taiwan, 
1012-1017, October 18-22 2010.

[C2] Lorenz Mösenlechner, Nikolaus Demmel and Michael Beetz, 
Becoming Action-aware through Reasoning about Logged Plan Execution Traces, 
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2231-2236, October 18-22 2010.
Cogito: Plan-based Control of Robotic Agents

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[J1] Alexandra Kirsch,  
_robot learning language – integrating programming and learning for cognitive systems_,  

[C1] Andreas Fedrizzi, Lorenz Mosenlechner, Freek Stulp and Michael Beetz,  
_transformational planning for mobile manipulation based on action-related places_,  

[C2] Lorenz Mosenlechner and Michael Beetz,  
_using physics- and sensor-based simulation for high-fidelity temporal projection of realistic robot behavior_,  
19th International Conference on Automated Planning and Scheduling (ICAPS’09), 2009.

[C1] Michael Beetz, Freek Stulp, Bernd Radig, Jan Bandouch, Nico Blodow, Mihai Dolha, Andreas Fedrizzi, Dominik Jain, Uli Klang, Ingo Kresse, Alexis Maldonado, Zoltan Marton, Lorenz Mosenlechner, Federico Ruiz, Radu Bogdan Rusu and Moritz Tenorth,  
The Assistive Kitchen – A Demonstration Scenario for Cognitive Technical Systems,  
IEEE 17th International Symposium on Robot and Human Interactive Communication (RO-MAN), Muenchen, Germany, 1-8, 2008.

[C2] Lorenz Mosenlechner, Armin Muller and Michael Beetz,  
High Performance Execution of Everyday Pick-and-Place Tasks by Integrating Transformation Planning and Reactive Execution,  

[PhD1] Alexandra Kirsch,  
Integration of Programming and Learning in a Control Language for Autonomous Robots Performing Everyday Activities,  
Technische Universitaet Muenchen, 2008.

[PhD2] Armin Muller,  
Transformational Planning for Autonomous Household Robots using Libraries of Robust and Flexible Plans,  
Technische Universitaet Muenchen, 2008.

[C1] Michael Beetz, Jan Bandouch, Alexandra Kirsch, Alexis Maldonado, Armin Muller and Radu Bogdan Rusu,  
The Assistive Kitchen — A Demonstration Scenario for Cognitive Technical Systems,  
Cogito: Plan-based Control of Robotic Agents

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[C2] Alexandra Kirsch and Michael Beetz,
Training on the Job — Collecting Experience with Hierarchical Hybrid Automata,

[C3] Armin Müller, Alexandra Kirsch and Michael Beetz,
Transformational Planning for Everyday Activity,

[C4] Armin Müller and Michael Beetz,
Towards a Plan Library for Household Robots,

[C1] Alexandra Kirsch and Michael Beetz,
Combining Learning and Programming for High-Performance Robot Controllers,

[C2] Alexandra Kirsch,
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[C3] Alexandra Kirsch, Michael Schweitzer and Michael Beetz,
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[C1] Michael Beetz, Alexandra Kirsch and Armin Müller,
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[C2] Armin Müller, Alexandra Kirsch and Michael Beetz,
Object-oriented Model-based Extensions of Robot Control Languages,
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