KnowRob: Knowledge processing for robots List of Publications


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[C5] Moritz Tenorth and Michael Beetz, 
Knowledge Processing for Autonomous Robot Control, 

[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer, 
Semantic Object Maps for Household Tasks, 

[C7] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr, 
CRAM – a Cognitive Robot Abstract Machine, 

[C8] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi, 
RoboEarth Action Recipe Execution, 

[C9] Moritz Tenorth and Michael Beetz, 
Exchange of Action-related Information among Autonomous Robots, 

[C10] Moritz Tenorth and Michael Beetz, 
A Unified Representation for Reasoning about Robot Actions, Processes, and their Effects on Objects, 

[C11] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz, 
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The SHERPA project: smart collaboration between humans and ground-aerial robots for improving rescuing activities in alpine environments, 
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[C13] Moritz Tenorth, Koji Kamei, Satoru Satake, Takahiro Miyashita and Norihiro Hagita, 
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[C3] Daniel Nyga, Moritz Tenorth and Michael Beetz,
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[C4] Nico Blodow, Zoltan-Csaba Marton, Dejan Pangercic, Thomas Rühr, Moritz Tenorth and Michael Beetz,
Inferring Generalized Pick-and-Place Tasks from Pointing Gestures,

[C5] Lars Kunze, Mihai Emanuel Dolha and Michael Beetz,
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