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[J1] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
**Representation and Exchange of Knowledge about Actions, Objects, and Environments in the RoboEarth Framework,** 

[C1] Charmayne Mary Lee Hughes, Moritz Tenorth, Marta Bienkiewicz and Joachim Hermsdörfer, 
**Action sequencing and error production in stroke patients with apraxia – Behavioral modeling using Bayesian Logic Networks,** 

[C2] Moritz Tenorth, Fernando De la Torre and Michael Beetz, 
**Learning Probability Distributions over Partially-Ordered Human Everyday Activities,** 

[J1] Zoltan-Csaba Marton, Florian Seidel, Ferenc Balint-Benczedi and Michael Beetz, 
**Ensembles of Strong Learners for Multi-cue Classification,** 
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[C2] Thomas Rühr, Jürgen Sturm, Dejan Pangercic, Michael Beetz and Daniel Cremers, 
**A Generalized Framework for Opening Doors and Drawers in Kitchen Environments,** 

[C3] Moritz Tenorth, Alexander Clifford Perzylo, Reinhard Lafrenz and Michael Beetz, 
**The RoboEarth language: Representing and Exchanging Knowledge about Actions, Objects, and Environments,** 

[C4] Lars Kunze, Michael Beetz, Manabu Saito, Haseru Azuma, Kei Okada and Masayuki Inaba, 
**Searching Objects in Large-scale Indoor Environments: A Decision-theoretic Approach,**  
[C5] Moritz Tenorth and Michael Beetz, 
Knowledge Processing for Autonomous Robot Control, 

[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer, 
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[C10] Moritz Tenorth and Michael Beetz, 
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[C7] Manabu Saito, Haseru Chen, Kei Okada, Masayuki Inaba, Lars Kunze and Michael Beetz,
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[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch,
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