KnowRob: Knowledge processing for robots List of Publications


[C1] Charmayne Mary Lee Hughes, Moritz Tenorth, Marta Bienkiewicz and Joachim Hermsdörfer, Action sequencing and error production in stroke patients with apraxia – Behavioral modeling using Bayesian Logic Networks, 6th International Conference on Health Informatics (HEALTHINF 2013), Barcelona, Spain, February 11–14 2013.


KnowRob: Knowledge processing for robots List of Publications

[C5] Moritz Tenorth and Michael Beetz,
Knowledge Processing for Autonomous Robot Control,

[C6] Michael Beetz, Moritz Tenorth, Dejan Pangercic and Benjamin Pitzer,
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[C7] Michael Beetz, Lorenz Mösenlechner, Moritz Tenorth and Thomas Rühr,
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[C8] Daniel di Marco, Moritz Tenorth, Kai Häussermann, Oliver Zweigle and Paul Levi,
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[C9] Moritz Tenorth and Michael Beetz,
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[C10] Moritz Tenorth and Michael Beetz,
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[C11] Dejan Pangercic, Moritz Tenorth, Benjamin Pitzer and Michael Beetz,
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[C13] Moritz Tenorth, Koji Kamei, Satoru Satake, Takahiro Miyashita and Norihiro Hagita,
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[C3] Daniel Nyga, Moritz Tenorth and Michael Beetz, 
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KnowRob: Knowledge processing for robots List of Publications

[J1] Michael Beetz, Moritz Tenorth, Dominik Jain and Jan Bandouch, 
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[C2] Moritz Tenorth and Michael Beetz, 
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